# Aerodynamic Theory for a Cascade of **Oscillating Airfoils in Subsonic Flow**

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The theory is developed in terms of the velocity potential rather than the acceleration potential, and a brief outline is given of the simple numerical technique used. The effects of varying airfoil spacing, frequency, Mach number, stagger angle, and phase difference between adjacent airfoils are discussed. Particular attention is given to variations in the aerodynamic damping for pure vertical translational and pitching motions. It is shown that the translational damping can become zero at certain discrete frequencies but that it never becomes negative. The pitching moment damping, however, can become negative over a wide range of frequencies of practical interest. The airfoils are assumed to be at zero mean incidence.

solved.

## Introduction

ANY research workers have published papers on the theory of incompressible flow through a cascade of oscillating airfoils representing the blades of an axial compressor, and on the airloads induced by oscillatory inlet flow, but not as many have taken compressibility effects into account. Much of the work done for incompressible flow conditions has been reviewed by Meister 1 and by Schorr and Ready.<sup>2</sup> References to the most significant papers are given and the different methods of solution used are briefly discussed. However, the present paper is principally concerned with compressibility effects, though the theory and techniques developed can also be applied to incompressible flow as a limiting case when  $M\rightarrow 0$ . The general numerical method of solution employed is extremely simple to use and it enables the research worker to obtain meaningful and accurate results without getting involved in the very complex mathematics required in the analytical treatment of the cascade problem.

Much of the earlier work 5-8 on airfoils in cascade has been done in relation to either in-phase oscillations or to the determination of wall interference effects on measurements of airloads on oscillating airfoils in wind tunnels. The latter problem has been considered by many authors for incompressible flow conditions, but the literature on the corresponding compressible flow problem is somewhat scanty. Runyan<sup>9</sup> and his co-workers at NASA Langley investigated the problem and showed that it was possible to get tunnel resonance at certain critical frequencies. In an independent study, W.P. Jones 10 determined the airloads on a particular airfoil describing pitching oscillations and compared his results with those measured in a subsonic wind tunnel after making allowance for wall effects. More recently, investigations of subsonic flow through cascades of airfoils have been made in relation to vibration problems of axial compressors. Fleeter, 11 for instance, has considered the case of oscillatory inlet flow on a row of staggered airfoils at various Mach numbers up to M = 0.9 for a range of frequencies and selected angles. The simple technique used in this paper has recently been applied to the same problem and the results obtained have been reported in Ref. 12. Good agreement was obtained in all cases with Fleeter's results. 11

The present paper is, however, concerned with the equally important problem of determining the airload coefficients for

an individual blade of a cascade of oscillating blades or air-

foils. It summarizes work previously described in Ref. 13 and

gives a selection of the results included in that study in a

revised form. To preserve generality, a typical row of com-

pressor blades is represented as in Fig. 1, where the blades are

assumed to be staggered, to be oscillating out of phase, and to

be spaced apart at specified distances. In order to determine

the airloads on a typical airfoil of such a cascade, a method

similar to that developed in Ref. 14 was used. The integral

equation that one has to solve is replaced by a set of

simultaneous equations that can readily be solved to give the

required information. In the analysis, the downwash induced

at the reference airfoil by the doublet distribution over each

oscillating blade of the cascade is represented by a com-

plicated series of Hankel functions denoted by  $S_0$ . This series,

in the form in which it initially arises, is poorly convergent.

Fortunately, however, it has been shown in Refs. 15 and 16

that it can be replaced by a rapidly convergent series of ex-

ponential terms. By using the alternative exponential form of

 $S_0$  and its derivative  $S_1$  ( $\equiv \partial S_0/\partial x$ ) the problem can easily be

with reduced frequency up to the first critical frequency. Un-

der certain conditions, it was also discovered that the pitching

moment damping could be negative. This suggests that, for

It was found that all the airload coefficients varied rapidly

CASCADE OF AEROFOILS

† z

Fig. 1 Cascade of airfoils.

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certain combinations of the relevant parameters, Mach number, frequency, spacing, stagger, etc., the airfoils might be unstable and that a one-degree-of-freedom type of oscillation could develop. It is also indicated that care must be taken to use the appropriate airload coefficients in any flutter study since they are very sensitive to some of the parameters involved.

#### **Outline of Analysis**

The analysis is developed for the cascade of oscillating airfoils illustrated in Fig. 1. The reference airfoil, with its center at the origin of coordinates, is assumed to be describing plunging and pitching oscillations of frequency p rad/sec defined by  $z(=\ell z'e^{ipt})$  and  $\alpha(=\alpha'e^{ipt})$  respectively. In general, it may also be assumed that the mth airfoil of the cascade has a phase lead of  $m\sigma'$ , where  $\sigma'(=2\pi\delta')$  represents the difference in phase between adjoining airfoils. The distance between the mean positions of the leading edges of the airfoils is taken to be s and the stagger angle is assumed to be s0. The vertical spacing between the airfoils is then s1.

Let us next transform the coordinates into a nondimensional form by writing

$$x = \ell X$$
,  $z = \ell Z/\beta$ , and  $t = \ell T/U$  (1)

where  $\beta = (I - M^2)^{\frac{1}{2}}$ . The downwash at any point  $X_l$ , 0 on the reference airfoil is then given by  $w(X_l, T)$  ( $\equiv w'(X_l)$ ) where

$$w'(X_I) = U[i\omega(z' + X_I\alpha') + \alpha']$$
 (2)

and  $\omega = p\ell/U$  is the reduced frequency parameter. If the velocity potention  $\phi$  of the flow is now replaced by a modified velocity potential  $\Phi$  such that

$$\phi = U\ell \Phi e^{i(\lambda X + \omega T)} \tag{3}$$

where  $\lambda = M^2 \omega / \beta^2$ , it may be deduced that

$$\partial^2 \Phi / \partial X^2 + \partial^2 \Phi / \partial Z^2 + \kappa^2 \Phi = 0 \tag{4}$$

where  $\kappa = M\omega/\beta^2$ . It also follows from Eq. (3) that the modified downwash distribution corresponding to  $w'(X_I)$  of Eq. (2) is

$$W(X_I) = \frac{\partial \Phi}{\partial Z} = \frac{w'(X_I)e^{-i\lambda X_I}}{U\beta}$$
 (5)

The corresponding formula for the local lift distribution  $\ell(X)$  may also be expressed in the form

$$\ell(X) = \rho U^2 \left( ivK + \partial K / \partial X \right) e^{i(\lambda X + \omega T)} \tag{6}$$

where  $K(\equiv \Phi_a - \Phi_b)$  denotes the discontinuity in the modified velocity potential and the parameter  $v = \omega/\beta^2$ . The appropriate solution of Eq. (4), which satisfies the boundary condition defined by Eq. (5), may then be obtained from the integral equation

$$2\pi W(X_I, Z_I) = -\int_{-I}^{\infty} K(X) \frac{\partial^2}{\partial Z_I^2} S_0(X_I - X, Z_I, S, \lambda_M, \sigma) dX$$
(7)

where

$$S_0 = \frac{\pi i}{2} \sum_{m=-\infty}^{\infty} e^{im\sigma} H_0^{(2)} \left\{ \kappa \left[ (X_I - X + mD)^2 + (mH - Z_I)^2 \right]^{\frac{1}{2}} \right\}$$
(8)

 $\sigma = \sigma' + \lambda D = 2\pi\delta$  is the modified phase difference and  $Z_1$ ,0 on the reference airfoil. It should be noted that  $\sigma$  is dependent on the actual phase shift  $\sigma'$  between adjacent blades, the Mach number, frequency, spacing, and stagger angle. The

symbols  $D(=d/\ell)$  and  $H(=\beta h/\ell)$  in Eq. (8) correspond to S sin  $\lambda_M$  and  $S \cos \lambda_M$  respectively where  $\tan \lambda_M = \beta^{-1} \tan \lambda_o$  and  $S = [D^2 + H^2]^{\frac{1}{2}}$ . In Ref. 16, the series of Hankel Functions defined by Eq. (8) is replaced by a series of exponential terms of the form

 $S_0 =$ 

$$-\frac{1}{2}\sum_{n=-\infty}^{\infty}\frac{\exp[-2i\xi(\delta-n)\sin\lambda_{M}-2|\xi|[(\delta-n)^{2}-\mu^{2}]^{\frac{1}{2}}\cos\lambda_{M}]}{(\bar{\delta}-n)^{2}-\mu^{2}]^{\frac{1}{2}}}$$
(9)

where  $\xi = \pi (X_I - X)/S$  and  $\mu = \kappa S/\pi$ . Evidently, this series becomes divergent whenever

$$\mu = \delta, 1 \pm \delta, ..., n \pm \delta, ...$$

or

$$\kappa S = \sigma' + \lambda D, 2\pi \pm (\sigma' + \lambda D), \text{ etc } \dots$$
 (10)

and, at each of these critical values of  $\mu$  (or  $\kappa S$ ), no solution is possible. The alternative form of Eq. (10) has also been given in Ref. 17 except that the sign of  $\sigma'$ , the phase shift between the blades, is opposite to that assumed in this paper. From Eq. (10), the critical or "resonance" frequencies can readily be deduced.

In both papers listed as Ref. 13, the fact that  $\sigma(=2\pi\delta)$  was the *modified* phase difference was overlooked. Consequently, Eq. (17) of the first paper and the curves in Fig. 2 of the second paper require correction. The critical reduced frequencies can be derived from Eq. (10) and are given by

$$\omega_c = (2\pi n + \sigma') \left[ (I - M^2 \cos^2 \lambda_\theta)^{1/2} + M \sin \lambda_\theta \right] \ell / M s$$
 (11)

and

$$\omega_c = (2\pi n - \sigma') [(I - M^2 \cos^2 \lambda_0)] \ell / Ms$$
 (12)

where n=0, 1, 2, 3, etc., and only positive values of  $\omega_c$  are

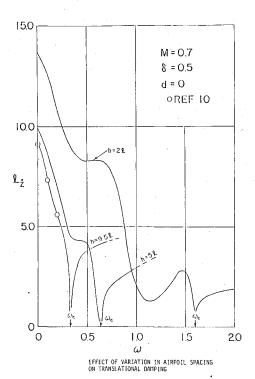


Fig. 2 Effect of variation in airfoil spacing on translational damping for  $\lambda_0 = 0$ .

considered. In Ref. 13 it is shown that Eq. (7) can be replaced by

$$2\pi W(X_I) = \int_{-I}^{I} K(X) \left[ \frac{\partial S_I}{\partial X} + \kappa^2 S_0 \right] dX + K_T I$$
 (13)

where  $K_T$  is the value of K at the trailing edge, X=I, and  $S_I = \partial S_0 / \partial X$ . In the wake  $K(X) = K_T \exp[-iv(X-I)]$ , and it can be deduced that

$$I = -S_{1T} - ivS_{0T} - v^2 (I - M^2)P$$
 (14)

where

$$P = -\frac{1}{2} \sum_{n=-\infty}^{\infty} \frac{S \exp[-2\pi \bar{a}(n) (1 - X_1) / S]}{[2\pi \bar{a}(n) + i \nu S][(\delta - n)^2 - \mu^2]^{\frac{1}{2}}}$$
(15)

and  $\tilde{a}(n) = [(\delta - n)^2 - \mu^2]^{\frac{1}{2}} \cos \lambda_M - i(\delta - n) \sin \lambda_M$ . The terms  $S_{0T}$  and  $S_{1T}$  respectively denote the values of  $S_0$  and  $S_1$  at the trailing edge. By dividing the reference airfoil into N equal strips of width 2b and assuming K to be constant over each strip, Eq. (13) can be reduced to a linear set of simultaneous equations when the boundary condition is satisfied at the center of each strip. The values of  $K_n$  ( $n=1,2,\ldots,N$ ) will then give the required K distribution. In Eq. (13), as suggested in Ref. 13,  $K_T$  is assumed to be given approximately by

$$K_T = \frac{K_N}{2ivb + \exp(-ivb)} \tag{16}$$

where 2b is the width of each strip. This relation is derived by imposing the condition of no lift at the trailing edge and in the wake, namely  $ivK + \partial K/\partial X = 0$ , and expressing it in finite difference form.

Once the  $K_n$  values have been determined, the lift L (= $L'e^{ipt}$ ) and nose-up pitching moment  $M(=M'e^{ipt})$  about half-chord can be deduced. In terms of aerodynamic coefficients, they are conveniently expressed as

$$L'/\rho U^2 \ell = (\ell_r + i\omega \ell_r) z' + (\ell_\alpha + i\omega \ell_\alpha) \alpha'$$
 (17a)

and

$$M'/\rho U^2 \ell^2 = (m_z + i\omega m_z) z' + (\omega_\alpha + i\omega m_\alpha) \alpha'$$
 (17b)

where the values of  $\ell_z$ ,  $\ell_z$  etc. can be calculated. The direct damping coefficients,  $\ell_z$ , and  $-m_{\dot{\alpha}}$ , are of primary importance in stability studies. The effects of varying various parameters on these particular coefficients were investigated and some of the results obtained will next be discussed. When the reference axis is changed to quarter-chord, the coefficients in Eq. (17) are replaced by barred coefficients  $\bar{\ell}_z$ ,  $\bar{\ell}_z$  etc.

## **Discussion of Results**

In the two reports listed as Ref. 13, a considerable amount of detailed information on the behavior of the aerodynamic coefficients  $\ell_z$ ,  $\ell_z$  etc. is given. Such information would be required in any proposed study of the flutter characteristics of a cascade of airfoils but until now very little has been available. This lack of data is probably due to the fact that the methods of computation used, such as the Lane & Friedman method, <sup>17</sup> require substantial computing time and are prohibitively expensive as far as the systematic tabulation of aerodynamic coefficients is concerned.

Because of space limitations, only a few selected results from Ref. 13 are presented in this paper. Those given in Ref. 13 for staggered blades are given for constant values of  $\sigma$  rather than  $\sigma'$ , the actual phase difference. The present paper contains some results for the latter case. Attention is prin-

cipally concentrated on the damping aerodynamic coefficient,  $\ell_i$ , for vertical translational oscillations and  $-\bar{m}_{\dot{\alpha}}$ , the pitching damping coefficient referred to the quarter-chord axis position. For instance, Fig. 2 shows the effect on  $\ell_2$  of varying the airfoil spacing when M=0.7, the airfoils are 180° out of phase, and  $\lambda_0 = 0$ . The main effect of increasing the spacing between the airfoils results in a decrease in the first critical frequency,  $\omega_c$ , for which  $\ell_i = 0$ . As  $\omega$  increases, the damping decreases rapidly to zero at  $\omega = \omega_c$  and then increases again as  $\omega$  is increased without becoming negative. Below the first critical frequency, the damping decreases when the spacing between the airfoils is increased. When  $h = 9.5\ell$ , which corresponds to the case of an airfoil in a wind tunnel, the values of  $\ell_z$ , check with results obtained previously by a different method. <sup>10</sup> The variation in  $\ell_r$  with phase difference and frequency is shown in Fig. 3 for the case when M = 0.7,  $h = 2\ell$ and  $\lambda_0 = 0$ . For  $0 < \omega < \omega_c$ , the damping decreases rapidly as  $\omega$ is increased. A reduction in phase difference also results in a loss of damping for the lower values of  $\omega$ . It should be noted that the first critical frequency,  $\omega_c$ , is directly proportional to the phase difference. Figure 4 shows the effect of Mach number on  $\ell_{\tilde{\tau}}$  and the curves again reveal a rapid decrease in damping for the lower values of  $\omega$ , particular for M=0.9. The variation in  $\ell_2$  when the phase difference is reduced from 180° ( $\delta'$ 0.5) is shown in Fig. 5 for the case of M = 0.9 and a stagger angle of  $60^{\circ}$ . For the lower values of  $\omega$ , a reduction in phase difference results in a reduction in translational damping. Similarly, in Fig. 6, it is shown that an increase in stagger angle results in a decrease in  $\ell_z$  when  $\omega$  is small  $(\omega \leq 0.1)$ .

Some typical results for the pitching moment damping coefficient  $-\bar{m}_{\alpha}$ , referred to the quarter-chord axis are illustrated in Fig. 7-11. When M=0.7 and  $\lambda_0=0$ , the damping can be negative when the phase difference between the motions of the airfoils is greater than 60° ( $\delta'=1/6$ ) as shown in Fig. 7. When  $\delta'=1/2$ , the damping is negative over the range  $1.0<\omega \le 1.6$ , the upper value corresponding to the first "resonance" frequency. By decreasing the phase difference the region of potential instability is reduced until at  $\delta'=1/6$ , it almost disappears. The effect of Mach number is shown in Fig. 8, where it is revealed that, for the case considered, the region of negative damping is increased as Mach number is increased.

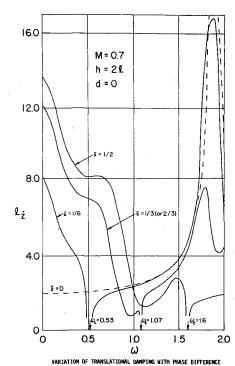


Fig. 3 Variation of translational damping with phase difference for  $\lambda_0 = 0$ .

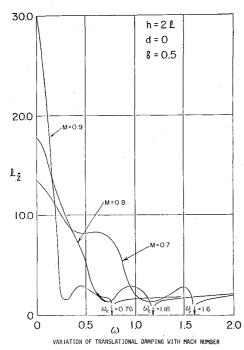


Fig. 4 Variation of translational damping with Mach number for  $\lambda_{\theta} = 0$ .

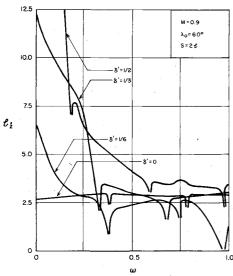


Fig. 5 Effect of variation in phase on translational damping when  $\lambda_0 = 60^{\circ}$ .

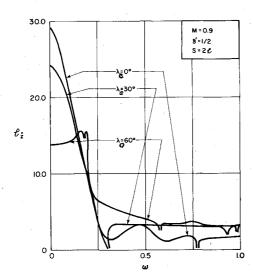


Fig. 6 Effect of variation in stagger angle on translational damping.

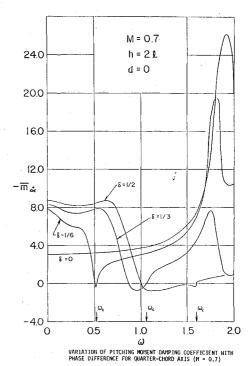


Fig. 7 Variation of pitching moment damping coefficient with phase difference for quarter-chord axis for  $\lambda_\theta=0$  and M=0.

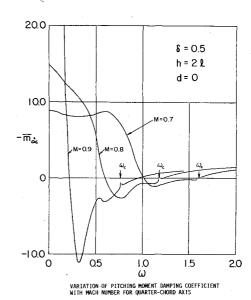


Fig. 8 Variation of pitching moment damping coefficient with Mach number for quarter-chord axis for  $\lambda_{\theta}=0$ .

For M=0.9, the area of potential instability is extensive and the curve of  $-\bar{m}_{\dot{\alpha}}$  shows a minimum value at about  $\omega=0.3$ . The phase difference for this case was 180° and the airfoils were unstaggered. The effect of decreasing the phase difference is shown in Fig. 9. It reveals that a decrease in the phase difference would be beneficial. Figure 10 shows the variation in the damping  $-\bar{m}_{\dot{\alpha}}$  when the airfoils are staggered and  $\lambda_0=30^\circ$ . For the worst case considered, namely when M=0.9 and  $\delta'=1/2$ , Fig. 11 indicates that increasing the staggered angle would result in a reduction in the area of instability and would lessen the danger of flutter. It might, however, be worthwhile to carry out a full flutter analysis, using the appropriate aerodynamic coefficients, and comparing the results with those obtained by Whithead 18 by the use of Smith's method. 19

Theoretical studies of blade vibration in axial compressors are often made by replacing the blades by a cascade of closely

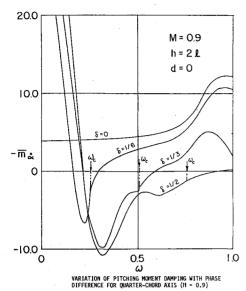


Fig. 9 Variation of pitching moment damping with phase difference for quarter-chord axis for  $\lambda_0 = 0$  and M = 0.9.

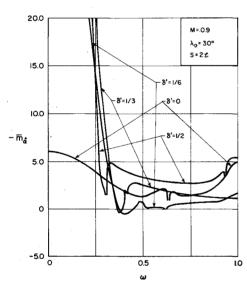


Fig. 10 Variation of pitching moment damping with phase lag for  $\lambda_{\theta} = 30^{\circ}$ .

spaced airfoils. Such a representation by a two-dimensional cascade may be too idealized as in an actual compressor the speed of flow varies along the span of the blade. Blade tip effects and internal structural damping are also present that might tend to suppress theoretically predicted vibrations.

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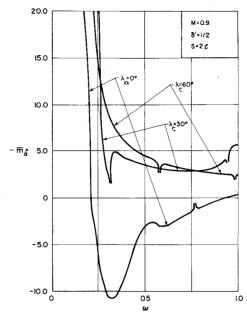


Fig. 11 Variation of pitching moment damping coefficient with stagger angle.

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